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Research Article

General Traveling Wave Solutions of Nonlinear Conformable Fractional Sharma-Tasso-Olever Equations and Discussing the Effects of the Fractional Derivatives

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The exact traveling wave solution of the fractional Sharma-Tasso-Olever equation can be obtained by using the function expansion method, but the general traveling wave solution cannot be obtained. After transforming it into the Sharma-Tasso-Olever equation of the integer order by the fractional complex transformation, the general solution of its traveling wave is obtained by a specific function transformation. Through parameter setting, the solution of the kinked solitary wave is found from the general solution of the traveling wave, and it is found that when the two fractional derivatives become smaller synchronically, the waveform becomes more smooth, but the position is basically unchanged. The reason for this phenomenon is that the kink solitary wave reaches equilibrium in the counterclockwise and clockwise rotation, and the stretching phenomenon is accompanied in the process of reaching equilibrium. This is a further development of our previous work, and this kind of detailed causative analysis is rare in previous papers.

1. Introduction

Because of many phenomena, integer-order differential equations cannot be well described, which makes fractional nonlinear differential equations have research significance. As an effective mathematical modeling tool, it is widely used in the mathematical modeling of nonlinear phenomena in biology, physics, signal processing, control theory, system recognition, and other scientific fields. The widely studied fractional Sharma-Tasso-Olever (STO) equation in space and time [1–4]

$$\frac{\partial^{\alpha} u}{\partial t^{\alpha}} + 3\rho u^{2} \frac{\partial^{\beta} u}{\partial x^{\beta}} + 3\rho \left(\left[\frac{\partial^{\beta} u}{\partial x^{\beta}} \right]^{2} + u \frac{\partial^{2\beta} u}{\partial x^{2\beta}} \right) \right) + \rho \frac{\partial^{3\beta} u}{\partial x^{3\beta}} = 0, 0 < \alpha \le 1, 0 < \beta \le 1.$$
(1)

In equation (1), if $\alpha = \beta$, we get [5]

$$\frac{\partial^{\alpha} u}{\partial t^{\alpha}} + 3\rho u^{2} \frac{\partial^{\alpha} u}{\partial x^{\alpha}} + 3\rho \left(\left[\frac{\partial^{\alpha} u}{\partial x^{\alpha}} \right]^{2} + u \frac{\partial^{2\alpha} u}{\partial x^{2\alpha}} \right) + \rho \frac{\partial^{3\alpha} u}{\partial x^{3\alpha}} = 0.$$
(2)

In equation (1), if $\beta = 1$, we get the time-fractional STO equation [6, 7]

$$D_t^{\alpha} u + 3\rho u^2 u_x + 3\rho u_x^2 + 3\rho u u_{xx} + \rho u_{xxx} = 0, 0 < \alpha \leq 1. \quad (3)$$

In equations (1)–(3), u = u(x, t) is the function to be solved, ρ is an arbitrary real parameter, and α , β are conformable fractional derivatives.

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Recently, we have looked at some papers that obtain the exact solutions of the traveling wave of fractional-order equations and have illustrated some solitary wave solutions contained in the exact traveling wave solutions. These articles used different methods to obtain a large number of accurate traveling wave solutions in various forms. In order to better understand our work, we present the definitions and properties of the conformable fractional derivative as follows.

Given a function $f:[0,\infty] \to R$. Then, the conformable fractional derivative of f of order $0 < \alpha < 1$ is defined as [8]

$$T_{\alpha}(f)(t) = \lim_{\varepsilon \to 0} \frac{f(t + \varepsilon t^{1-\alpha}) - f(t)}{\varepsilon}.$$
 (4)

The conformable derivative is a fractal derivative [9]. According to the fractal derivative theory, the influence of environmental abnormal fluctuation on physical behavior is equivalent to the influence of fractal space-time transformation [10, 11]. Several properties of conformable fractional derivative definition are as follows:

$$\begin{split} T_{\alpha}(af+bg) &= aT_{\alpha}(f) + bT_{\alpha}(g), \text{ for all } a,b \in R, \\ T_{\alpha}(C) &= 0, \\ T_{\alpha}\left(t^{b}\right) &= bt^{b-\alpha}, \text{ for all } b \in R, \\ T_{\alpha}(fg) &= gT_{\alpha}(f) + fT_{\alpha}(g), \\ &\text{ if } f \text{ is differentiable, } T_{\alpha}(f)(t) = t^{1-a}\frac{df}{dt}(t). \end{split}$$

These properties have been proved in literature [8], and there is no need to repeat them here. The physical interpretation of the conformable fractional derivative can be found in the literature [12].

According to Theorem 2.11 (chain Rule) in literature [13], we show the following properties of consistent fractional derivatives.

$$T_{\alpha}^{t}f(g(t)) = f_{q}'(g(t))g'(t)t^{1-\alpha}.$$
 (6)

For more detailed knowledge, refer to literature [13]. Formula (6) is briefly proved as follows.

Proof. Set $u = t + \varepsilon t^{1-\alpha}$ in the definition, and you get

$$T_{\alpha}^{t}f(g(t)) = \lim_{u \to t} \frac{f(g(u)) - f(g(t))}{u - t} t^{1-\alpha}$$

$$= \lim_{u \to t} \frac{f(g(u)) - f(g(t))}{g(u) - g(t)} \cdot \lim_{u \to t} \frac{g(u) - g(t)}{u - t} t^{1-\alpha}$$

$$= \lim_{g(u) \to g(t)} \frac{f(g(u)) - f(g(t))}{g(u) - g(t)} \cdot \lim_{u \to t} \frac{g(u) - g(t)}{u - t} t^{1-\alpha}$$

$$= f_{g}'(g(t))g'(t)t^{1-\alpha}.$$
(7)

Now, let us look at some of the work with the STO equation of fractional order to find the exact traveling wave solution. In literature [1], the author used fractional complex transformation for equation (1) and then used the expfunction method to obtain its precise traveling wave solution.

In literature [2], the author used fractional complex transformation on equation (1) and then used (G'/G^2) -expansion method to obtain the precise traveling wave solution of equation (1).

In literature [3], the author used fractional complex transformation on equation (1) and then used the novel (G'/G)-expansion method to obtain the exact traveling wave solution of equation (1); the generalized Kudryashov method was also used to obtain the precise traveling wave solution of equation (1).

In literature [4], the author used the improved (G'/G) -expansion method to get the exact traveling wave solution of equation (1) after using the complex fractional transformation.

In literature [5], the author used fractional complex transformation for equation (2), and then extended tanhcoth method was used to obtain the precise traveling wave solution of equation (2).

In literature [6], the author used fractional complex transformation for equation (3) and then used the Riccadi function expansion method to obtain the exact traveling wave solution of fractional-order equation (3).

In literature [7], the author used fractional complex transformation in equation (3) and then used a new generalized (G'/G)-expansion method to obtain the precise traveling wave solution of the fractal equation (3).

Here, we have just listed some of the articles on the accurate line-wave solution to the STO equation of fractional order. It can be seen from literature [1–7] that the first step of these authors was to reduce the STO equation of the fractional order to a nonlinear ordinary differential equation by using fractional complex transformation and then to solve the reduced equation by various methods to obtain the solution of the original fractional-order equation. In addition to the methods provided in literature [1–7], there are other techniques that can be used to obtain wave solutions of different structures [14–19]. It can be seen from equations (1)–(3) that the most general equation is equation (1), so we only discuss the accurate general traveling wave solution of equation (1).

For equation (1), α , β are conformable fractional derivatives and the fractional complex transformation used is [20]

$$u(x,t) = U(\xi), \xi = \frac{ct^{\alpha}}{\alpha} + \frac{kx^{\beta}}{\beta},$$
 (8)

where c, k are parameters to be determined. Through equation (8), equation (1) can be transformed into

$$cU' + 3k^2 \rho \left(U'\right)^2 + 3k^2 \rho UU'' + 3k\rho U^2 U' + k^3 \rho U''' = 0.$$
(9)

In literature [1-7], some articles integrate equation (13) once and then assume that the integral constant is zero,

which will lead to the exact solution obtained being less general than its original one [21, 22]. Equation (9) is a thirdorder differential equation, and in general, its general solution should contain three arbitrary constants. From this perspective, the exact line-wave solutions obtained in the article [1-7] we mentioned are not general solutions, but only partial solutions. In this paper, we consider the integrability of equation (9) and combine with the fractional complex transformation to obtain the general traveling wave solution of the fractional STO equation, which is different from the exact solution obtained by using the function expansion method in known literature. As we all know, from the exact solutions of traveling waves, various forms of solutions can be obtained by choosing appropriate parameters, such as soliton solutions and periodic wave solutions. This conclusion can be obtained by bifurcation analysis of the first integral equation of equation (9) [23]. If the reader wants to know how the exact linear wave solutions of equation (9) are bifurcated and how the exact traveling wave solutions correspond to different forms of solutions, please refer to [23]. We selected from the general solution of traveling wave a kink solitary wave to fractional-order parameter change on the influence of the waveform, found that when two fractional-order parameters decrease at the same time, the kink soliton will become more smooth, but the location remains the same basic phenomenon, through the analysis found that the cause of this phenomenon is a kink soliton in the clockwise and counterclockwise to balance. Papers with such detailed analysis are rare.

2. The General Solution of the Fractional STO Equation in Space and Time in the Traveling Wave

Substituting equation (8) into equation (1) for transformation, we get

$$cU' + 3k^2 \rho \left(U'\right)^2 + 3k^2 \rho UU'' + 3k\rho U^2 U' + k^3 \rho U''' = 0.$$
(10)

Integrate equation (10) once, and we get

$$cU + 3k^{2}\rho UU' + k\rho U^{3} + k^{3}\rho U'' + C_{0} = 0,$$
 (11)

where $U''' = dU/d\xi$, C_0 is the integral constant. Considering the specific function transformation,

$$U = \frac{kF'}{F},\tag{12}$$

where $F''' = dF/d\xi$, $F = F(\xi)$, we can easily get the following equation.

$$U' = k \frac{F'' F - (F')^{2}}{F^{2}},$$

$$UU' = k^{2} \frac{F'' F' F - (F')^{3}}{F^{3}},$$
(13)

$$U'' = k \frac{\left(F'''F + F''F' - 2F'F''\right)F - \left(F''F - \left(F'\right)^{2}\right)2F'}{F^{3}}.$$
(14)

Substituting equations (13) and (14) into equation (11), we get

$$ck\frac{F'}{F} + 3k^{4}\rho \frac{F''F'F - (F')^{3}}{F^{3}} + \rho k^{4} \frac{(F')^{3}}{F^{3}} + \rho k^{4} \frac{(F')^{3}}{F^{3}} + \rho k^{4} \frac{(F'''F + F''F' - 2F'F'')F - (F''F - (F')^{2})2F'}{F^{3}} + C_{0} = 0.$$
(15)

Arrange equation (15) to get

$$k\frac{F'}{F} + \rho k^4 \frac{F'''}{F} + C_0 = 0 \Rightarrow F''' + \frac{c}{\rho k^3} F' + \frac{C_0}{\rho k^4} F = 0$$
 (16)

Equation (16) is a familiar three-differential equation, and its general solution can be easily obtained, denoted as $p = c/\rho k^3 \neq 0$, $q = C_0/\rho k^4$; then, equation (16) has a characteristic equation

$$r^3 + pr + q = 0 (17)$$

The three roots of equation (17) can be obtained by Cardin formula in the following order:

$$r_{1} = \sqrt[3]{-\frac{q}{2} + \sqrt{\left(\frac{q}{2}\right)^{2} + \left(\frac{p}{3}\right)^{3}}} + \sqrt[3]{-\frac{q}{2} - \sqrt{\left(\frac{q}{2}\right)^{2} + \left(\frac{p}{3}\right)^{3}}},$$
(18)

$$r_{2} = \omega \sqrt[3]{ -\frac{q}{2} + \sqrt{\left(\frac{q}{2}\right)^{2} + \left(\frac{p}{3}\right)^{3}}} + \omega^{2} \sqrt[3]{ -\frac{q}{2} - \sqrt{\left(\frac{q}{2}\right)^{2} + \left(\frac{p}{3}\right)^{3}}},$$
(19)

$$r_{3} = \omega^{2} \sqrt[3]{-\frac{q}{2} + \sqrt{\left(\frac{q}{2}\right)^{2} + \left(\frac{p}{3}\right)^{3}}} + \omega \sqrt[3]{-\frac{q}{2} - \sqrt{\left(\frac{q}{2}\right)^{2} + \left(\frac{p}{3}\right)^{3}}},$$
(20)

where $\omega = (-1 + \sqrt{3}i)/2$.

(1) When discriminant $\Delta = (q/2)^2 + (p/3)^3 = 0$, that is, $(C_0)^2 = 4c^3/27\rho k$, the three roots of equation (17) are reduced to

$$r_1 = 2\sqrt[3]{-\frac{q}{2}}, r_2 = r_3 = \sqrt[3]{\frac{q}{2}}.$$
 (21)

equation (16) has the following general solution:

$$F(\xi) = C_1 e^{2\sqrt[3]{-(q/2)}\xi} + (C_2 + C_3 \xi) e^{\sqrt[3]{(q/2)}\xi}, \tag{22}$$

where C_1 , C_2 , and C_3 are arbitrary constants

Without loss of generality, we can assume C_1 is not equal to zero. By substituting equation (22) into equation (12) and combining with complex transformation equation (8), the general traveling wave solution of the original equation (1) is expressed as

$$\begin{split} U &= k \frac{C_1 2\sqrt[3]{-(q/2)} e^{2\sqrt[3]{-(q/2)}\xi} + \left(C_2\sqrt[3]{q/2} + C_3\sqrt[3]{(q/2)}\xi + C_3\right) e^{\sqrt[3]{(q/2)}\xi}}{C_1 e^{2\sqrt[3]{-(q/2)}\xi} + \left(C_2 + C_3\xi\right) e^{\sqrt[3]{(q/2)}\xi}} \\ &= k \frac{2\sqrt[3]{-(q/2)} e^{2\sqrt[3]{-(q/2)}\xi} + \left(C_2/C_1\sqrt[3]{q/2} + C_3/C_1\sqrt[3]{(q/2)}\xi + \left(C_3/C_1\right)\right) e^{\sqrt[3]{(q/2)}\xi}}{e^{2\sqrt[3]{-(q/2)}\xi} + \left(\left(C_2/C_1\right) + \left(C_3/C_1\right)\xi\right) e^{\sqrt[3]{(q/2)}\xi}}. \end{split}$$

In equation (23), there are only two arbitrary constants, which is caused by the fixed arbitrary constant C_0 . Without loss of generality, we could write $C_4 = C_2/C_1$, $C_5 = C_3/C_1$.

(2) When discriminant $\Delta = (q/2)^2 + (p/3)^3 \neq 0$, equation (19) has the following general solution:

$$F(\xi) = C_1 e^{r_1 \xi} + C_2 e^{r_2 \xi} + C_3 e^{r_3 \xi}, \tag{24}$$

where C_1 , C_2 , and C_3 are arbitrary constants

Without loss of generality, we can assume C_1 is not equal to zero. By substituting equation (24) into equation (12) and combining with complex transformation equation (8), the general traveling wave solution of the original equation (1) is expressed as

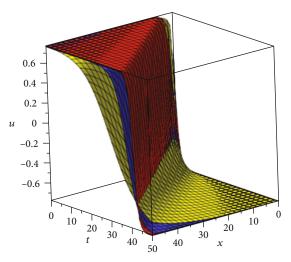
$$U = k \frac{C_{1}r_{1}e^{r_{1}\xi} + C_{2}r_{2}e^{r_{2}\xi} + C_{3}r_{3}e^{r_{3}\xi}}{C_{1}e^{r_{1}\xi} + C_{2}e^{r_{2}\xi} + C_{3}e^{r_{3}\xi}}$$

$$= k \frac{r_{1}e^{r_{1}\xi} + (C_{2}/C_{1})r_{2}e^{r_{2}\xi} + (C_{e}/C_{1})r_{3}e^{r_{3}\xi}}{e^{r_{1}\xi} + (C_{2}/C_{1})e^{r_{2}\xi} + (C_{3}/C_{1})e^{r_{3}\xi}}.$$
(25)

Without loss of generality, we could write $C_4 = C_2/C_1$, $C_5 = C_3/C_1$, and we have an arbitrary constant C_0 hidden in the parameter q.

3. The Discussion and Explanation

We observed some articles about the STO equation of fractional order and found that they more or less ignored the properties of the equation itself in the solution process, and



Solution (27) red: $\alpha = \beta = 1$, blue: $\alpha = \beta = 0.7$, yellow: $\alpha = \beta = 0.4$

FIGURE 1: 3D plot of solution (27) for various values of $\alpha = \beta$, and k = 1, $\rho = 2$, c = -1.2, $C_4 = C_5 = 1$.

the exact solution of the traveling wave obtained by various function expansion methods was not the general solution. Because in general, it makes sense that the precise general solution to equation (10) should contain three arbitrary constants. In the following part, we will find the kinked solitary wave solution from the general solution obtained in this paper and analyze the influence of the synchronous change of two fractional derivatives on the kinked solitary wave solution waveform and the reasons for this phenomenon.

Let ξ in equation (25) be the expression in equation (8), namely,

$$\xi = \frac{ct^{\alpha}}{\alpha} + \frac{kx^{\beta}}{\beta}.$$
 (26)

We take the integral constant C_0 in equation (11) as zero; then, r_1, r_2 , and r_3 in equation (25) are valued as $r_1 = 0, r_2 = \sqrt{-p} = \sqrt{-c/\rho k^3}, r_3 = -\sqrt{-p} = -\sqrt{-c/\rho k^3}$; then, equation (25) is rewritten as

$$\begin{split} U &= k \frac{r_1 e^{r_1 \xi} + (C_2/C_1) r_2 e^{r_2 \xi} + (C_3/C_1) r_3 e^{r_3 \xi}}{e^{r_1 \xi} + (C_2/C_1) e^{r_2 \xi} + (C_3/C_1) e^{r_3 \xi}} \\ &= k \frac{C_4 r_2 e^{r_2 \xi} + C_5 r_3 e^{r_3 \xi}}{1 + C_4 e^{r_2 \xi} + C_5 e^{r_3 \xi}} \\ &= k \frac{C_4 \sqrt{-c/\rho k^3}_2 e^{\sqrt{-c/\rho k^3} \left((ct^a/\alpha) + \left(kx^\beta/\beta \right) \right)} - C_5 \sqrt{-c/\rho k^3} e^{-\sqrt{-c/\rho k^3} \left((ct^a/\alpha) + \left(kx^\beta/\beta \right) \right)}}{1 + C_4 e^{\sqrt{-c/\rho k^3} \left((ct^a/\alpha) + \left(kx^\beta/\beta \right) \right)} + C_5 e^{-\sqrt{-c/\rho k^3} \left((ct^a/\alpha) + \left(kx^\beta/\beta \right) \right)}} \end{split}. \end{split}$$

In equation (27), take k = 1, $\rho = 2$, c = -1.2, $C_4 = C_5 = 1$; then, the diagram of solution (27) of equation (1) changing with $\alpha = \beta$ is shown in Figure 1. This is the kink solitary wave solution, which is a particular solution of the general solution (25) of equation (1). When $\alpha = \beta = 1$, the fractional-order STO equation degenerates into an equation of integer order. At this point, the diagram of

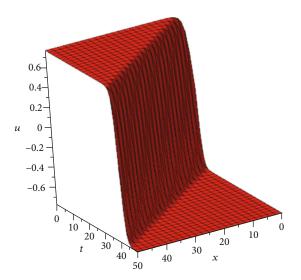
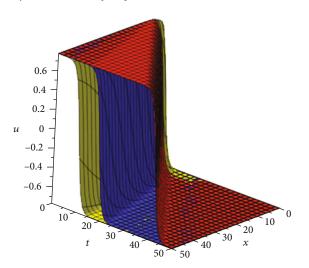


FIGURE 2: 3D plot of solution (27) for values of $\alpha = \beta = 1$, and k = 1, $\rho = 2$, c = -1.2, $C_4 = C_5 = 1$.

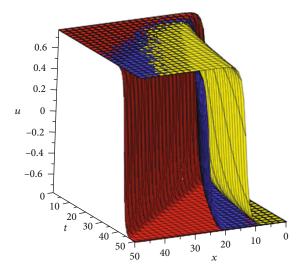


 $\alpha = 1$; solution (27) red: $\beta = 1$, blue: $\beta = 0.7$, yellow: $\beta = 0.4$

FIGURE 3: 3D plot of solution (27) for various values of β , and k = 1, $\rho = 2$, c = -1.2, $C_4 = C_5 = 1$.

equation (27) is taken from Figure 1, as shown in Figure 2. After setting values for other parameters, Figure 1 explains the perspective view of the solution (27), when the values of $\alpha = \beta$ are 1, 0.7, and 0.4 in turn.

As can be seen from Figure 1, as the fractional derivative α and β become smaller synchronically, the twist of the kink solitary wave becomes smoothed, but the position of the twist of the kink solitary wave basically remains at the straight line x=t on the t-x plane. In order to further explain this phenomenon and promote our previous work [24], this paper conducts a more detailed study of the influence of fractional derivative on the shape of kink solitary wave in two steps. First, the value of the time fractional derivative α is fixed, and only the change of the spatial fractional derivative β is observed. The result is shown in Figure 3. It can be seen from Figure 3 that the spatial fractional derivative β values 1, 0.7, and 0.4 in turn, and the kinked solitary wave rotates at the



 β = 1; solution (27) red: α = 1, blue: α = 0.7, yellow: α = 0.4

Figure 4: 3D plot of solution (27) for various values of α , and $k=1, \rho=2, c=-1.2, C_4=C_5=1.$

kinked position in the t-x plane, and the direction of rotation is close to the line t = 0 inside the t-x plane. Secondly, the value of the spatial fractional derivative β is fixed, and only the change of the time fractional derivative α is observed. The result is shown in Figure 4. It can be seen from Figure 4 that the time fractional derivative α is 1, 0.7, and 0.4 in turn, and the kinking position of the kink solitary wave in the t-x plane also rotates, with the direction approaching the line x = 0 in the x-t plane.

By comparing Figures 3 and 4, it is found that the spatial fractional derivative β becomes smaller, making the kink of the kink isolated wave as shown in the figure rotate clockwise in the t-x plane, while the time fractional derivative α becomes smaller, making the kink of the kink isolated wave as shown in the figure rotate counterclockwise in the t-x plane. When the fractional derivatives change synchronically, the kinks of the isolated wave in Figure 1 reach a balance in the clockwise rotation and counterclockwise rotation, and the position of the kinks almost stays the same. Meanwhile, the kinks of the isolated wave stretch together in the clockwise and counterclockwise rotation, which makes the kinks of the isolated wave smoothen.

4. Conclusion

The exact traveling wave solutions obtained by the function expansion method are usually not the general traveling wave solutions of fractional-order nonlinear partial differential equations. In this paper, the fractional-order STO equation is transformed into an integer-order STO equation through the complex fractional-order transformation, and then, the general traveling wave solution of the fractional-order STO equation is obtained through the transformation of a specific function, which will make our understanding of the traveling wave solution of the fractional-order STO equation more comprehensive. By setting parameters, a kinked solitary wave solution is extracted from the general traveling wave solution,

and the influence of the fractional derivative on the kinked solitary wave is analyzed in detail. It is found that the kinked solitary wave becomes more smooth when the fractional-order parameters are synchronized, but the position of the kinked solitary wave is basically unchanged. The position of the kinked solitary wave is basically unchanged because we have two fractional-order parameters, one of which becomes smaller so that the kinked waveform rotates clockwise, and the other fractional-order parameter becomes smaller so that the kinked waveform rotates counterclockwise. Such clockwise rotation and counterclockwise rotation achieve a balance. The kink solitary wave becomes smoother because of the tugging phenomenon that accompanies the process of reaching equilibrium.

Data Availability

No data were used to support this study.

Conflicts of Interest

The authors declare that they have no conflicts of interest.

Authors' Contributions

All authors read and approved the final manuscript.

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